

Expanded Mark Scheme – Motors & Encoders

Q	Expanded Answer Guidance	Marks
1a	<p>Any 2 AC motors:</p> <ul style="list-style-type: none"> • Induction motor – simple, robust, low maintenance • Synchronous motor – constant speed • Single-phase motor – used in domestic applications <p>Accept any valid + characteristic</p>	4
1b	<ul style="list-style-type: none"> • Three-phase supply produces 3 currents 120° apart • Each creates a magnetic field • Fields combine to form rotating magnetic field • This induces current in rotor causing motion <p>Accept diagrams/explanations</p>	4
1c	<p>Effects of higher frequency (60 Hz):</p> <ul style="list-style-type: none"> • Increased speed (Ns proportional to frequency) • Possible overheating • Reduced torque • Mechanical stress <p>Accept:</p> <ul style="list-style-type: none"> • Any valid performance impact 	4
2a	<p>Any 5 parts:</p> <ul style="list-style-type: none"> • Armature • Commutator • Brushes • Field coils/magnets • Power Source <p>Accept equivalents</p>	5
2b	<ul style="list-style-type: none"> • Reverses current direction in armature • Maintains continuous rotation • Ensures torque stays in same direction 	2

2c	<p>Shunt:</p> <ul style="list-style-type: none"> • Parallel winding • Constant speed <p>Series:</p> <ul style="list-style-type: none"> • Series winding • High starting torque <p>Accept comparisons</p>	3
3a	<ul style="list-style-type: none"> • Provide movement at joints • Convert electrical energy into mechanical motion • Enable positioning of arm 	2
3b	<ul style="list-style-type: none"> • Measure position/rotation of joints • Provide feedback to controller • Enable accurate positioning <p>Accept:</p> <ul style="list-style-type: none"> • Speed/position feedback 	3
3c	<p>Incremental:</p> <ul style="list-style-type: none"> • Provides relative position • Needs reference point <p>Absolute:</p> <ul style="list-style-type: none"> • Provides exact position • No reference needed <p>Appropriate:</p> <ul style="list-style-type: none"> • Absolute encoder (better for robotics) <p>Accept justification</p>	3
3d	<ul style="list-style-type: none"> • Dust blocks light paths • Reduces accuracy • Causes signal errors <p>Accept:</p> <ul style="list-style-type: none"> • Reliability issues in dirty environments 	3

3e	<p>Better option:</p> <ul style="list-style-type: none">• Magnetic encoder• Inductive encoder <p>Justification:</p> <ul style="list-style-type: none">• Resistant to dust• More robust in harsh environments <p>Accept equivalents</p>	3
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